High order three part split symplectic integrators. Application to the disordered discrete nonlinear Schrödinger equation

Haris Skokos

Department of Mathematics and Applied Mathematics, University of Cape Town Cape Town, South Africa

> E-mail: haris.skokos@uct.ac.za URL: http://www.mth.uct.ac.za/~hskokos/

This research has been co-financed by the European Union (European Social Fund – ESF) and Greek national funds through the Operational Program "Education and Lifelong Learning" of the National Strategic Reference Framework (NSRF) - Research Funding Program: Thales. Investing in knowledge society through the European Social Fund.



Outline

- Symplectic Integrators
- Disordered lattices
 - ✓ The quartic Klein-Gordon (KG) disordered lattice
 - ✓ The disordered discrete nonlinear Schrödinger equation (DNLS)
- Different integration schemes for DNLS
- Conclusions

Autonomous Hamiltonian systems

Let us consider an N degree of freedom autonomous Hamiltonian systems of the $H(\vec{q}, \vec{p}) = \frac{1}{2} \sum_{i=1}^{N} p_i^2 + V(\vec{q})$ form:

As an example, we consider the Hénon-Heiles system:

$$H_2 = \frac{1}{2}(p_x^2 + p_y^2) + \frac{1}{2}(x^2 + y^2) + x^2y - \frac{1}{3}y^3$$

Hamilton equations of motion:

Variational equations:

$$\begin{cases} \dot{x} = p_x \\ \dot{y} = p_y \\ \dot{p}_x = -x - 2xy \\ \dot{p}_y = y^2 - x^2 - y \end{cases}$$
$$\begin{cases} \dot{\delta x} = \delta p_x \\ \dot{\delta y} = \delta p_y \\ \dot{\delta p}_x = -(1+2y)\delta x - 2x\delta y \\ \dot{\delta p}_y = -2x\delta x + (-1+2y)\delta y \end{cases}$$

Symplectic Integrators (SIs)

Formally the solution of the Hamilton equations of motion can be written as: $\frac{d\vec{X}}{dt} = \left\{H, \vec{X}\right\} = L_H \vec{X} \Longrightarrow \vec{X}(t) = \sum_{n \ge 0} \frac{t^n}{n!} L_H^n \vec{X} = e^{tL_H} \vec{X}$

where \vec{X} is the full coordinate vector and L_H the Poisson operator:

$$L_{H}f = \sum_{j=1}^{N} \left\{ \frac{\partial H}{\partial p_{j}} \frac{\partial f}{\partial q_{j}} - \frac{\partial H}{\partial q_{j}} \frac{\partial f}{\partial p_{j}} \right\}$$

If the Hamiltonian H can be split into two integrable parts as H=A+B, a symplectic scheme for integrating the equations of motion from time t to time t+ τ consists of approximating the operator $e^{\tau L_H}$ by

$$\mathbf{e}^{\tau \mathbf{L}_{\mathrm{H}}} = \mathbf{e}^{\tau (\mathbf{L}_{\mathrm{A}} + \mathbf{L}_{\mathrm{B}})} = \prod_{i=1}^{\mathsf{J}} \mathbf{e}^{\mathbf{c}_{i} \tau \mathbf{L}_{\mathrm{A}}} \mathbf{e}^{\mathbf{d}_{i} \tau \mathbf{L}_{\mathrm{B}}} + O(\boldsymbol{\tau}^{\mathsf{n}+1})$$

for appropriate values of constants c_i , d_i . This is an integrator of order n. So the dynamics over an integration time step τ is described by a series of successive acts of Hamiltonians A and B.

Symplectic Integrator SABA₂C

The operator $e^{\tau L_H}$ can be approximated by the symplectic integrator [Laskar & Robutel, Cel. Mech. Dyn. Astr. (2001)]:

$$SABA_{2} = e^{c_{1}\tau L_{A}} e^{d_{1}\tau L_{B}} e^{c_{2}\tau L_{A}} e^{d_{1}\tau L_{B}} e^{c_{1}\tau L_{B}} e^{c_{1}\tau L_{B}} e^{c_{1}\tau L_{A}}$$

with $c_{1} = \frac{1}{2} \cdot \frac{\sqrt{3}}{6}, c_{2} = \frac{\sqrt{3}}{3}, d_{1} = \frac{1}{2}.$

The integrator has only small positive steps and its error is of order 2.

In the case where *A* is quadratic in the momenta and *B* depends only on the positions the method can be improved by introducing a corrector *C*, having a small negative step:

$$C = e^{-\tau^{3} \frac{c}{2} L_{\{\{A,B\},B\}}}$$

with $c = \frac{2 - \sqrt{3}}{24}$. Thus the full integrator scheme becomes: $SABAC_2 = C (SABA_2) C$ and its error is of order 4.

Tangent Map (TM) Method

Any symplectic integration scheme used for solving the Hamilton equations of motion, which involves the act of Hamiltonians A and B, can be extended in order to integrate simultaneously the variational equations [S. & Gerlach, PRE (2010) – Gerlach & S., Discr. Cont. Dyn. Sys. (2011) – Gerlach et al., IJBC (2012)].

The Hénon-Heiles system can be split as: $A = \frac{1}{2}(p_x^2 + p_y^2)$ $B = \frac{1}{2}(x^2 + y^2) + x^2y - \frac{1}{3}y^3$

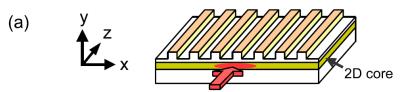
$$\begin{split} \dot{x} &= p_{x} \\ \dot{y} &= p_{y} \\ \dot{y} &= p_{y} \\ \dot{p}_{x} &= -x - 2xy \\ \dot{p}_{y} &= y^{2} - x^{2} - y \end{split} \xrightarrow{A(\vec{p})} \xrightarrow{\dot{x}} A(\vec{p}) \\ \dot{p}_{y} &= 0 \\ \dot{p}_{y} &= 0 \\ \dot{p}_{y} &= 0 \\ \dot{p}_{y} &= 0 \\ \dot{\delta}x &= \delta p_{x} \\ \dot{\delta}y &= \delta p_{y} \\ \dot{\delta}y &= \delta p_{y} \\ \dot{\delta}y &= \delta p_{y} \\ \dot{\delta}y &= -(1 + 2y)\delta x - 2x\delta y \\ \dot{\delta}p_{y} &= -2x\delta x + (-1 + 2y)\delta y \end{aligned} \right\} \Rightarrow \frac{d\vec{u}}{dt} = L_{BV}\vec{u} \Rightarrow e^{\tau L_{BV}} : \begin{cases} x' &= x + p_{x}\tau \\ y' &= y + p_{y}\tau \\ px' &= p_{x} \\ py' &= p_{y} \\ \delta x' &= \delta x + \delta p_{x}\tau \\ \delta y' &= \delta p_{y} \\ \delta p_{y} &= 0 \\ \delta p_{y} &= 0 \end{cases} \right\}$$

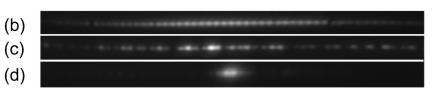
Interplay of disorder and nonlinearity

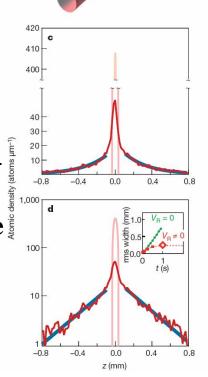
Waves in disordered media – Anderson localization [Anderson, Phys. Rev. (1958)]. Experiments on BEC [Billy et al., Nature (2008)]

Waves in nonlinear disordered media – localization or delocalization?

Theoretical and/or numerical studies [Shepelyansky, PRL (1993) – Molina, Phys. Rev. B (1998) – Pikovsky & Shepelyansky, PRL (2008) – Kopidakis et al., PRL (2008) – Flach et al., PRL (2009) – S. et al., PRE (2009) – Mulansky & Pikovsky, EPL (2010) – S. & Flach, PRE (2010) – Laptyeva et al., EPL (2010) – Mulansky et al., PRE & J.Stat.Phys. (2011) – Bodyfelt et al., PRE (2011) – Bodyfelt et al., IJBC (2011)] Experiments: propagation of light in disordered 1d waveguide lattices [Lahini et al., PRL (2008)]







<u>The Klein – Gordon (KG) model</u>

$$H_{K} = \sum_{l=1}^{N} \frac{p_{l}^{2}}{2} + \frac{\tilde{\varepsilon}_{l}}{2} u_{l}^{2} + \frac{1}{4} u_{l}^{4} + \frac{1}{2W} (u_{l+1} - u_{l})^{2}$$

with fixed boundary conditions $u_0 = p_0 = u_{N+1} = p_{N+1} = 0$. Typically N=1000.

Parameters: W and the total energy E. $\tilde{\varepsilon}_l$ chosen uniformly from $\left[\frac{1}{2}, \frac{3}{2}\right]$.

<u>Linear case</u> (neglecting the term $u_l^4/4$)

Ansatz: $u_l = A_l \exp(i\omega t)$. Normal modes (NMs) $A_{v,l}$ - Eigenvalue problem: $\lambda A_l = \varepsilon_l A_l - (A_{l+1} + A_{l-1})$ with $\lambda = W\omega^2 - W - 2$, $\varepsilon_l = W(\tilde{\varepsilon}_l - 1)$

The discrete nonlinear Schrödinger (DNLS) equation

We also consider the system:

$$\boldsymbol{H}_{D} = \sum_{l=1}^{N} \varepsilon_{l} \left| \boldsymbol{\psi}_{l} \right|^{2} + \frac{\boldsymbol{\beta}}{2} \left| \boldsymbol{\psi}_{l} \right|^{4} - \left(\boldsymbol{\psi}_{l+1} \boldsymbol{\psi}_{l}^{*} + \boldsymbol{\psi}_{l+1}^{*} \boldsymbol{\psi}_{l} \right)$$

where ε_l chosen uniformly from $\left[-\frac{W}{2}, \frac{W}{2}\right]$ and β is the nonlinear parameter.

Conserved quantities: The energy and the norm $S = \sum_{l} |\psi_{l}|^{2}$ of the wave packet.

Distribution characterization

We consider normalized energy distributions in normal mode (NM) space

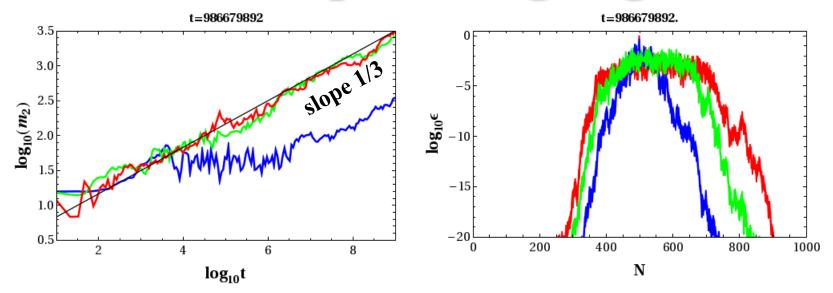
$$z_v \equiv \frac{E_v}{\sum_m E_m}$$
 with $E_v = \frac{1}{2} \left(\dot{A}_v^2 + \omega_v^2 A_v^2 \right)$, where A_v is the amplitude

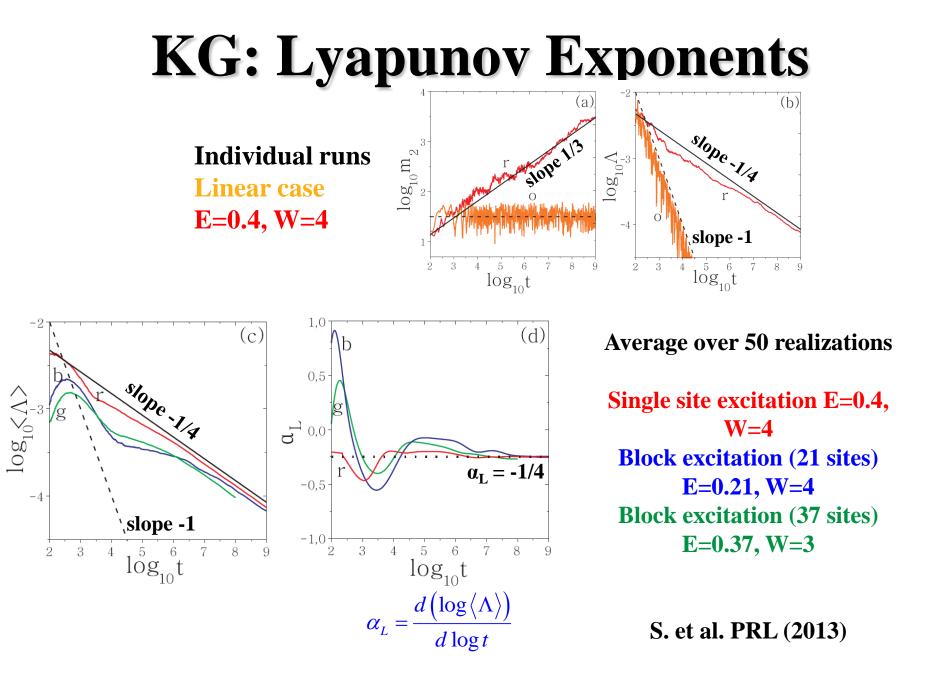
of the vth NM.

Second moment:

$$\boldsymbol{n}_2 = \sum_{\nu=1}^N (\nu - \overline{\nu})^2 \boldsymbol{z}_{\nu} \quad \text{with} \quad \overline{\nu} = \sum_{\nu=1}^N \nu \boldsymbol{z}_{\nu}$$

Different spreading regimes





The KG model

We apply the SABAC₂ integrator scheme to the KG Hamiltonian by using the splitting:

with a corrector term which corresponds to the Hamiltonian function:

$$\mathbf{C} = \left\{ \left\{ A, B \right\}, B \right\} = \sum_{l=1}^{N} \left[u_{l} (\tilde{\varepsilon}_{l} + u_{l}^{2}) - \frac{1}{W} (u_{l-1} + u_{l+1} - 2u_{l}) \right]^{2}$$

The DNLS model

A 2nd order SABA Symplectic Integrator with 5 steps, combined with approximate solution for the *B* part (Fourier Transform): SIFT²

$$\begin{split} H_{D} &= \sum_{l} \varepsilon_{l} |\psi_{l}|^{2} + \frac{\beta}{2} |\psi_{l}|^{4} \cdot (\psi_{l+1}\psi_{l}^{*} + \psi_{l+1}^{*}\psi_{l}), \quad \psi_{l} = \frac{1}{\sqrt{2}} (q_{l} + ip_{l}) \\ H_{D} &= \sum_{l} \left(\frac{\varepsilon_{l}}{2} (q_{l}^{2} + p_{l}^{2}) + \frac{\beta}{8} (q_{l}^{2} + p_{l}^{2})^{2} \cdot q_{n}q_{n+1} - p_{n}p_{n+1} \right) \\ A & B \\ e^{\tau L_{A}} : \begin{cases} q_{l}' = q_{l} \cos(\alpha_{l}\tau) + p_{l} \sin(\alpha_{l}\tau), \\ p_{l}' = p_{l} \cos(\alpha_{l}\tau) - q_{l} \sin(\alpha_{l}\tau), \\ \alpha_{l} = \epsilon_{l} + \beta(q_{l}^{2} + p_{l}^{2})/2 \end{cases} e^{\tau L_{B}} : \begin{cases} \varphi_{q} = \sum_{m=1}^{N} \psi_{m}e^{2\pi i q(m-1)/N} \\ \varphi_{q}' = \varphi_{q}e^{2i\cos(2\pi (q-1)/N)\tau} \\ \psi_{l}' = \frac{1}{N}\sum_{q=1}^{N} \varphi_{q}'e^{-2\pi i l(q-1)/N} \end{cases} \end{split}$$

The DNLS model

Symplectic Integrators produced by Successive Splits (SS)

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\beta}{8} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{n}q_{n+1} - p_{n}p_{n}p_{n+1} \right)$$

$$H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right) + \frac{\varepsilon_{l}}{l^{2}} \left(q_{l}^{2} + p_{l}^{2} \right)^{2} - q_{l}^{2}q_{l}^{2} - q_{l}^{2} -$$

Using the SABA₂ integrator we get a 2nd order integrator with 13 steps, SS²: $\begin{bmatrix} (3-\sqrt{3}) \\ \tau \end{bmatrix}_{L_A} \tau_{T_A} \sqrt{3\tau_A} \begin{bmatrix} (3-\sqrt{3}) \\ \tau \end{bmatrix}_{L_A} \tau_{T_A} \sqrt{3\tau_A} \tau_{T_A} \sqrt{3$

$$SS^{2} = e^{\begin{bmatrix} 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ 6 & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} \\ e^{\begin{bmatrix} (3-\sqrt{3}) & \sqrt{3} & \sqrt$$

Non-symplectic methods for the DNLS model

In our study we also use the DOP853 integrator which is an explicit non-symplectic Runge-Kutta integration scheme of order 8.

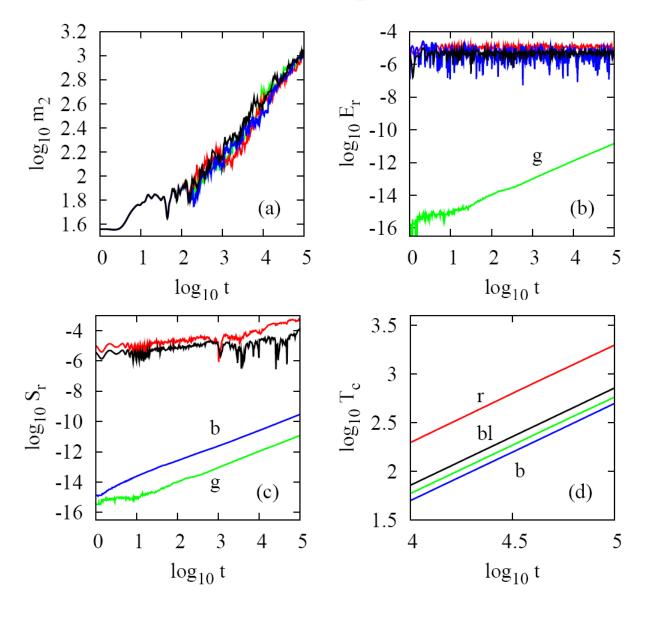
> DOP853: Hairer et al. 1993, http://www.unige.ch/~hairer/software.html

Three part split symplectic integrators for the DNLS model

Three part split symplectic integrator of order 2, with 5 steps: ABC² $H_{D} = \sum_{l} \left(\frac{\varepsilon_{l}}{2} (q_{l}^{2} + p_{l}^{2}) + \frac{\beta}{8} (q_{l}^{2} + p_{l}^{2})^{2} - q_{n}q_{n+1} - p_{n}p_{n+1} \right)$ $A \qquad B \qquad C$ $ABC^{2} = e^{\frac{\tau}{2}L_{A}} e^{\frac{\tau}{2}L_{B}} e^{\tau L_{C}} e^{\frac{\tau}{2}L_{B}} e^{\frac{\tau}{2}L_{A}}$

This low order integrator has already been used by e.g. Chambers, MNRAS (1999) – Goździewski et al., MNRAS (2008).

2nd order integrators: Numerical results



ABC² τ=0.005 SS² τ=0.02 DOP853 δ =10⁻¹⁶ SIFT² τ=0.05

E_r: relative energy error S_r: relative norm error T_c: CPU time (sec)

S. et al., Phys. Lett. A (2014)

Composition Methods: 4th order SIs

Starting from any 2nd order symplectic integrator S^{2nd}, we can construct a 4th order integrator S^{4th} using the composition method proposed by Yoshida [Phys. Lett. A (1990)]:

$$S^{4th}(\tau) = S^{2nd}(x_1\tau) \times S^{2nd}(x_0\tau) \times S^{2nd}(x_1\tau), \quad x_0 = -\frac{2^{1/3}}{2 - 2^{1/3}}, \quad x_1 = \frac{1}{2 - 2^{1/3}}$$

In this way, starting with the 2nd order integrators SS², SIFT² and ABC² we construct the 4th order integrators:

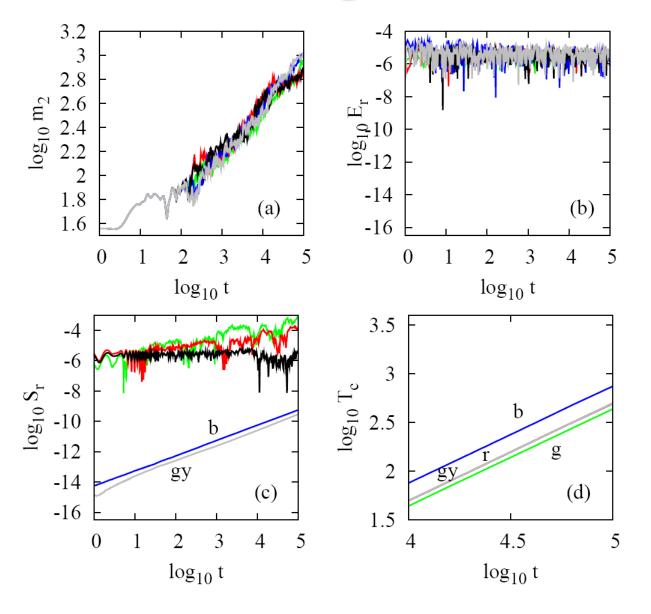
SS⁴ with 37 steps SIFT⁴ with 13 steps ABC⁴_[Y] with 13 steps

Composition method proposed by Suzuki [Phys. Lett. A (1990)]:

$$S^{4th}(\tau) = S^{2nd}(p_{2}\tau) \times S^{2nd}(p_{2}\tau) \times S^{2nd}((1-4p_{2})\tau) \times S^{2nd}(p_{2}\tau) \times S^{2nd}(p_{2}\tau)$$
$$p_{2} = \frac{1}{4-4^{1/3}}, \quad 1-4p_{2} = -\frac{4^{1/3}}{4-4^{1/3}}$$

Starting with the 2nd order integrators ABC² we construct the 4th order integrator: ABC⁴_[S] with 21 steps.

4th order integrators: Numerical results



SIFT⁴ τ =0.125 SIFT² τ =0.05 ABC⁴_[S] τ =0.1 SS⁴ τ =0.1 ABC⁴_[Y] τ =0.05

E_r: relative energy error S_r: relative norm error T_c: CPU time (sec)

S. et al., Phys. Lett. A (2014)

High order composition methods (I)

Using a composition technique introduced by Yoshida [Phys. Let. A (1990)] we construct the 6^{th} order symplectic integrator $ABC_{[Y]}^{6}$ having 29 steps :

 $ABC^{6}(\tau) = ABC^{2}(w_{3}\tau) \times ABC^{2}(w_{2}\tau) \times ABC^{2}(w_{1}\tau) \times ABC^{2}(w_{0}\tau) \times ABC^{2}(w_{1}\tau) \times ABC^{2}(w_{1}\tau) \times ABC^{2}(w_{2}\tau) \times ABC^{2}(w_{3}\tau)$

whose coefficients $w_1 = -1$.

 $w_{1} = -1.17767998417887$ $w_{2} = 0.235573213359357$ $w_{3} = 0.784513610477560$ $w_{0} = 1 - 2(w_{1} + w_{2} + w_{3})$

cannot be given in analytic form.

High order composition methods (II)

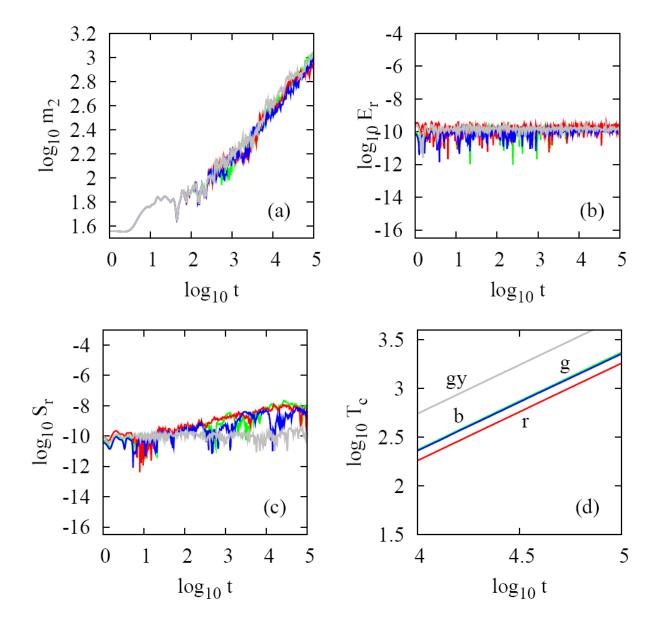
In addition, following the works of Kahan & Li, Math Comput. (1997), and Sofroniou & Spaletta, Optim. Methods Softw. (2005) we implement some efficient high order composition methods, considering as the basic block the 2nd order ABC² integrator.

> ABC⁶_[KL] with 37 steps ABC⁶_[SS] with 45 steps

> ABC⁸_[Y] with 61 steps ABC⁸_[KL] with 69 steps ABC⁸_[SS] with 77 steps

ABC¹⁰_[SS] with 125 steps

High order integrators: Numerical results (I)

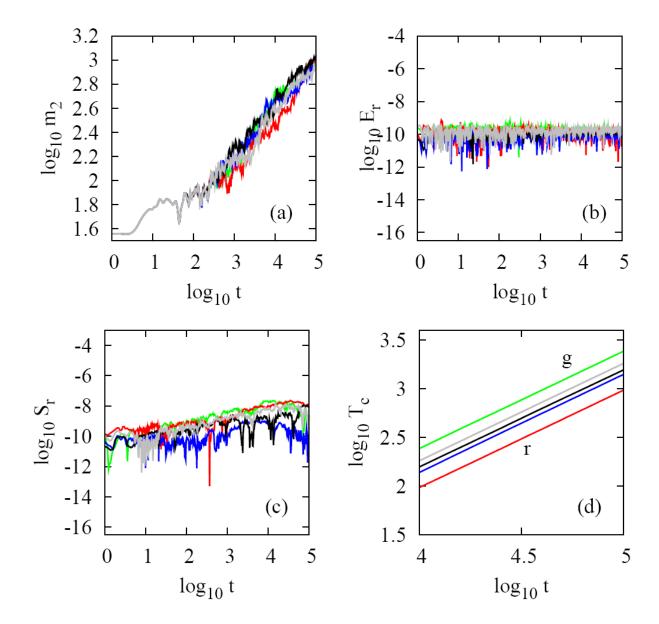


 $SS_{864}^{4} \tau = 0.015625$ $ABC_{[Y]}^{6} \tau = 0.03$ $ABC_{[KL]}^{6} \tau = 0.04$ $ABC_{[SS]}^{6} \tau = 0.125$

E_r: relative energy error S_r: relative norm error T_c: CPU time (sec)

S. et al., Phys. Lett. A (2014)

High order integrators: Numerical results (II)



 $ABC^{8}_{[Y]} \tau = 0.0625$ $ABC^{6}_{[SS]} \tau = 0.125$ $ABC^{10}_{[SS]} \tau = 0.2$ $ABC^{8}_{[KL]} \tau = 0.125$ $ABC^{8}_{[SS]} \tau = 0.2$

E_r: relative energy error S_r: relative norm error T_c: CPU time (sec)

S. et al., Phys. Lett. A (2014)

Summary

- We presented several efficient integration methods suitable for the integration of the DNLS model, which are based on symplectic integration techniques.
- The construction of symplectic schemes based on 3 part split of the Hamiltonian was emphasized (ABC methods).
- Algorithms based on the integration of the B part of Hamiltonian via Fourier transforms, i.e. methods SIFT² and SIFT⁴ succeeded in keeping the relative norm error S_r very low. Drawback: they require the number of lattice sites to be 2^k, k∈N*.
- We hope that our results will initiate future research both for the theoretical development of new, improved 3 part split integrators, as well as for their applications to different dynamical systems.

References

- Flach, Krimer, S. (2009) PRL, 102, 024101
- S., Krimer, Komineas, Flach (2009) PRE, 79, 056211
- S., Flach (2010) PRE, 82, 016208
- Laptyeva, Bodyfelt, Krimer, S., Flach (2010) EPL, 91, 30001
- Bodyfelt, Laptyeva, S., Krimer, Flach (2011) PRE, 84, 016205
- Bodyfelt, Laptyeva, Gligoric, S., Krimer, Flach (2011) Int. J. Bifurc. Chaos, 21, 2107
- S., Gkolias, Flach (2013) PRL, 111, 064101
- Tieleman, S., Lazarides (2014) EPL, 105, 20001
- S., Gerlach (2010) PRE, 82, 036704
- Gerlach, S. (2011) Discr.Cont. Dyn. Sys.-Supp. 2011, 475
- Gerlach, Eggl, S. (2012) Int. J. Bifurc. Chaos, 22, 1250216
- Gerlach, Eggl, S., Bodyfelt, Papamikos (2013) nlin.CD/1306.0627
- S., Gerlach, Bodyfelt, Papamikos, Eggl (2014) Phys. Lett. A, 378, 1809

Thank you for your attention